Yarden As

Research Scientist

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Portuguese and Israeli citizenship



About

I am inspired by science and how it can be applied in real life to contribute to society and human well-being. Naturally curious about tech and about people.

Education

Sep 2019 – MSc, Robotics, Systems and Control, ETH Zürich, Zürich, Switzerland.

Sep 2021 Focusing on machine learning and algorithms for online decision making.

• Scored a mark of 6.0/6.0 for my master's thesis with Prof. Andreas Krause.

Oct 2014 - BSc, Mechanical Engineering, Technion, Haifa, Israel.

Feb 2018 • Formal class ranking: #3 out of 156 students; top 3% during all semesters; graduated summa cum laude.

Experience

Aug 2021 - Research Scientist, Learning & Adaptive Systems group, Zürich.

Present • Developed a state of the art algorithm for safe reinforcement learning, significantly outperforming previous methods.

Mar 2021 – CTO, Co-Founder, CTO, Obol, Tel-Aviv.

Present Obol is a SaaS solution that helps enterprises optimize their multi-currency cash-flow.

• Devised Obol's strategy from the technological challenges perspective to solve an open-ended problem. This led to a \$750K pre-seed fundraise.

Sep 2019 - Principal Software Engineer, Robotemi, Tel-Aviv.

Jul 2021 Led the development of the product's new generation software stack.

- Developed autonomy stack deployed in one of the **few profitable** consumer robotics products. This work enabled the robot to **robustly** navigate and interact in **uncertain** domains such as exhibitions.
- My code runs on tens of thousands of units worldwide.

Feb 2018 - **Software Engineer**, *Robotemi*, Tel-Aviv.

Sep 2019 Developed **computer vision** algorithms for an indoor robotic application.

• My path-planning module implementation increased the navigation task success rate across the company's robot fleet from less than 65% to ~90%.

Skills (Selected)

Software C++ (proficient), Python (proficient), code optimization, ML frameworks (Tensorflow, JAX, Torch)...

Relevant Machine Learning (Introduction & Advanced), Probabilistic Artificial Intelligence, Deep Reinforcement coursework Learning (Berkeley CS285), Dynamic Programming and Optimal Control.

Other Strong interpersonal relations that translate into **fruitful collaborations** with different stakeholders.

Publications

• "Constrained Policy Optimization via Bayesian World Models." Yarden As, Ilnura Usmanova, Sebastian Curi, Andreas Krause. In International Conference on Learning Representations (ICLR), 2022, spotlight talk (~150/3500).

Awards and Honors

Technion KLA-Tencor merit-based scholarship; given annualy to the highest ranking student in class.

Technion M. Darlo award; given to the best final project in class.

Other

Trad rock climber; climbed a 200m high route in Wadi Rum, in charge of our protection from A to Z.